

4E2054

Roll No. _____

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B. Tech. IV Sem. (Back) Exam., June/July-2014
Mechanical Engineering
4ME6 Mechanical Measurements & Control
Common for Mech., Engg. & Automobile Engineering

Time: 3 Hours**Maximum Marks: 80****Min. Passing Marks: 24****Instructions to Candidates:-**

Attempt any five questions, selecting one question from each unit. All Questions carry equal marks. Schematic diagrams must be shown wherever necessary. Any data you feel missing suitably be assumed and stated clearly.

Units of quantities used/ calculated must be stated clearly.

Use of following supporting material is permitted during examination.

1. NIL2. NIL**UNIT - I**

Q.1 (a) Derive an expression for the output from the full bridge arrangement of strain gauges. [8]

(b) What is use at dummy gauge? Explain how do they effect the output of a strain gauge bridge. [8]

OR

Q.1 (a) Explain active and passive instruments, giving example of each. Discuss the merits of active and passive elements. [8]

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[4340]

- (b) Explain the method of calibration of strain gauges. [8]

UNIT - II

- Q.2 (a) Describe the working principle, construction and method of using an optical pyrometer with the help of neat diagram. [8]
- (b) Explain with neat sketches the working, construction, advantages and disadvantages of resistance thermometer. [8]

OR

- Q.2 What is a thermocouple? Name any two types of thermocouples. Describe with the help of diagram the construction and working of a thermocouple type pyrometer. [16]

UNIT - III

- Q.3 (a) Distinguish between open loop and closed loop control systems with the help of a suitable diagram. Illustrate your answer using block diagram schematics. [8]
- (b) What does signal flow graph represent? Define the various terms associated with it. List and graphically represent the different rules to simplify a given signal flow graph. [8]

OR

- (a) Describe in detail analog and digital data acquisition system. [8]
- (b) Explain the type of software used for data analysis. [8]

UNIT - IV

- Q.4 (a) Derive the transient response of a unit input first order system. [8]
- (b) Specify the time response specifications with the help of a diagram. [8]

OR

Q.4 (a) The forward loop of a unity feedback control system is given by -

$$G(S) = \frac{K}{S(S+6)}$$

Determine the value of K above which the system exhibits oscillatory behavior and obtains the output for K=8 and K=13 for a unit step input. [8]

(b) Discuss the operation of a position control serve mechanism employing dc motor and obtain its transfer function. [8]

UNIT - V

Q.5 (a) The characteristic equation for a certain feedback control system at input $S^4+43S^3+133S^2+36S+K=0$. Determine the range of value of K for the system to be stable. [8]

(b) Explain absolute and relative stability of a system. Discuss Routh and Hurwitz criterion for stability. [8]

OR

Q.5 (a) Sketch the root locus

$$G(s)H(s) = \frac{K}{S(S+1+j)(S+1-j)} \quad [8]$$

(b) Explain the effect of addition of open loop poles and zeros in root locus and stability. [8]